CS-206 Concurrency

Lecture 7 Synchronization Constructs

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Where are We?

		Lecture		
		& Lab		
Μ	Т	W	Т	F
16-Feb	17-Feb	18-Feb	19-Feb	20-Feb
23-Feb	24-Feb	25-Feb	26-Feb	27-Feb
2-Mar	3-Mar	4-Mar	5-Mar	6-Mar
9-Mar	10-Mar	11-Mar	12-Mar	13-Mar
16-Mar	17-Mar	18-Mar	19-Mar	20-Mar
23-Mar	24-Mar	25-Mar	26-Mar	27-Mar
30-Mar		1-Apr	2-Apr	3-Apr
6-Apr	7-Ap	8-Apr	9-Apr	10-Apr
13-Apr	14-Apr	15-Apr	16-Apr	17-Apr
20-Apr	21-Apr	22-Apr	23-Apr	24-Apr
27-Apr	28-Apr	29-Apr	30-Apr	1-May
4-May	5-May	6-May	7-May	8-May
11-May	12-May	13-May	14-May	15-May
18-May	19-May	20-May	21-May	22-May
25-May	26-May	27-May	28-May	29-May

- Hardware atomics
- Sophisticated primitives
 - ▷ Semaphores
 - \triangleright Monitors
 - ▷ Conditional variables
- Common problems
 - ▷ Bounded buffer
 - ▷ Readers-Writers
 - ▷ Dining Philosophers
- Next lecture (after break)
 Mid-term

Synchronization Hardware

- Many systems provide hardware support for critical section
- Old days: Uniprocessors disabled interrupts
 - Currently running code executes without preemption
 Too inefficient on multiprocessors
- Today all machines provide atomic instructions
 - ▷Atomic = non-interruptable
 - \triangleright Either test memory word and set value
 - ▷ Or swap contents of two memory words
- Recent machines provide support for transactions
 - ▷ Transaction = atomic instruction sequence
 - ▷ All memory changes visible before/after but not during

Solution to Critical-section Problem Using Locks

acquire lock
critical section
release lock

Definition

```
boolean Test&Set (boolean *target)
{
    boolean rv = *target;
    *target = TRUE;
    return rv;
}
```

Solution using Test&Set

- Shared boolean variable lock, initialized to FALSE
- Solution

while (TestAndSet (&lock))
 ; // do nothing
// critical section

lock = FALSE;

Definition

```
void Swap (boolean *a, boolean *b)
{
    boolean temp = *a;
    *a = *b;
    *b = temp;
}
```

Solution using Swap

- Shared Boolean variable lock initialized to FALSE
 Each process has a local Boolean variable key
- Solution

```
key = TRUE;
while ( key )
     Swap ( &lock, &key );
// critical section
lock = FALSE;
```

Examples in modern instruction sets

Oracle SPARC ISA

▷ swap [reg1], reg2 // swap contents at address reg1 w/ reg2

► Intel x86

▷ xchg [regI], reg2 // swap contents at address regI w/ reg2

Threads wait spinning

▷ Constantly reading/writing to/from the lock

 \triangleright Traffic out of the caches through the bus

 \triangleright Bus is a queue: > 50% utilization -> response time exponential

Not fair

 \triangleright There is no queue

 \triangleright Any thread can be next independent of waiting

Traffic



Bus Traffic vs. Waiting Time: M/M/I Queue



Test&Test&Set

```
do {
  while (lock)
     ; // test spinning in cache
       // lock is 0
} while ( TestAndSet ( &lock ));
// critical section
lock = FALSE;
```

Test&Swap

```
do {
  key = TRUE;
  while (lock)
     ; // test spinning in cache
       // lock is FALSE, quick!
  Swap ( &lock, &key );
} while ( key );
// critical section
lock = FALSE;
```

Traffic



Semaphore

- A high-level abstraction
- Semaphore S: an integer variable
- Two standard operations modify S

```
▷ wait() & signal()
```

 \triangleright Originally called P () & V ()

Can only be accessed via two indivisible (atomic) operations

```
wait (S) {
    while (S <= 0)
    ; // no-op
    S--;
}</pre>
```

Example Implementation with Test&Set

```
wait(semaphore s) {
 done = FALSE; //done is a local variable
 do {
  while(s <= 0 || TestAndSet(&lock))</pre>
     ; // do nothing
  if (s > 0) {
   done = TRUE;
   s--;
                       signal(semaphore s){
                        while(TestAndSet(&lock))
  lock=FALSE;
                            ; /* do nothing */
 } while (!done);
                        s++;
                        lock=FALSE;
```

Old days on uniprocessors: disabling/enabling interrupts

Modern systems:

Variety of ways including hardware primitives
 Test&Set, Swap, Transactional Memory (Intel Haswell)

From now on, assume wait & signal are atomic
 All of the operation is performed indivisibly

Binary Semaphore

- Counting semaphore: integer ranging over unrestricted domain
- Binary semaphore: integer values of 0 or 1; simpler to implement
 Also known as mutex locks
- Can implement a counting semaphore S as a binary semaphore
- Provides mutual exclusion

```
Semaphore mutex; // initialized to 1
wait (mutex);
// Critical Section
signal (mutex);
```

Simple Use of Semaphores: Rendez-Vous

Semaphore rendezvous; // initialized to 0

Thread I

Thread 2

// critical section l
signal (rendezvous);

wait (rendezvous);
// critical section 2

Semaphore with Busy Waiting

- Busy waiting is not the best use of resources
 Operating system (OS) can run other threads
- For each wait, there has to be signal
 To satisfy liveness
- Counting semaphores also suffer from fairness
 No notion when a thread arrived

Semaphore without Busy Waiting

- With each semaphore there is a waiting queue
 linked list
- Each entry in a waiting queue has two data items:
 value (of type integer)
 - \triangleright pointer to next record in the list
- ► Two OS operations:
 - block places the process invoking the operation on the appropriate waiting queue
 - >wakeup removes one of processes in the waiting queue and place it in the ready queue

Semaphore with Queues (atomic Wait & Signal)

```
Wait (and queue):
     wait(semaphore *S) {
      S->value--;
      if (S \rightarrow value < 0) {
                                             Atomic
            add this thread to S->list;
           block();
Signal (and wakeup):
     signal(semaphore *S) {
      S->value++;
      if (S \rightarrow value <= 0) {
           remove a thread P from S->list;
                                              Atomic
           wakeup(P);
```

Deadlock & Starvation

Let S and Q be two semaphores initialized to I



Deadlock and Starvation

Starvation

- ⊳ Indefinite blocking
- Thread may never be removed from the semaphore queue in which it is suspended

Priority Inversion

Scheduling problem when lower-priority thread holds a lock needed by higher-priority thread

▷ Solved via priority (inheritance) protocol

Classical problems solved via semaphores
 Bounded-Buffer Problem
 Readers and Writers Problem
 Dining-Philosophers Problem

- I buffer that holds N items
- Semaphore mutex initialized to value I
- Semaphore full initialized to value 0
- Semaphore empty initialized to value N

```
do {
    // produce an item in nextp
    wait (empty);
    wait (mutex);
    // add the item to the buffer
    signal (mutex);
    signal (full);
} while (TRUE);
```





```
do {
    // produce an item in nextp
    wait (empty);
    wait (mutex);
    // add the item to the buffer
    signal (mutex);
    Give permission
    signal (full);
    while (TRUE);
```

```
do {
   // produce an item in nextp
   wait (empty);
   wait (mutex);
   // add the item to the buffer
   signal (mutex);
   Announce an
   signal (full);
   while (TRUE);
```

```
do {
   wait (full);
   wait (mutex);
   // remove an item from buffer to
      nextc
   signal (mutex);
   signal (empty);
   // consume the item in nextc
} while (TRUE);
```





```
do {
   wait (full);
   wait (mutex);
   // remove an item from buffer to
        nextc Give permission
        signal (mutex);
        to other threads
        signal (empty);
        // consume the item in nextc
   while (TRUE);
```
Bounded-Buffer Problem (Cont.)

► The structure of the consumer thread

```
do {
   wait (full);
   wait (mutex);
   // remove an item from buffer to
    nextc Announce an
   signal (mutex); item was
   signal (empty);
   // consume the item in nextc
} while (TRUE);
```

Readers-Writers Problem

Data set shared among concurrent threads

 Readers only read the data set – no updates
 Writers can both read and write

 Multiple readers can read at the same time

 Only single writer can access shared data at same time

Shared Data

⊳Data set

- ▷ Semaphore mutex initialized to I
- ▷ Semaphore wrt initialized to I
- \triangleright Integer readcount initialized to 0

- Reader-Writer decisions:
- When is the writer done?
- When are the readers done?
- Must do book-keeping:
- The first reader waits on wrt to allow the writer to finish
 Other readers go through
- The last reader signals on wrt to allow the writer to start
 Other readers go through

► The structure of a writer thread

```
do {
   wait(wrt);
   // writing is performed
   signal (wrt);
} while (TRUE);
```

► The structure of a writer thread



► The structure of a writer thread











```
The structure of a reader thread
     do {
        wait (mutex) ;
        readcount ++ ;
        if (readcount == 1)
           wait (wrt) ;
        signal (mutex)
        // reading is performed
        wait (mutex) ;
                               If you are the last reader
        readcount -- ;
                               give permission to other
        if (readcount == 0)
                                       threads
           signal (wrt) ;
        signal (mutex) ;
       while (TRUE);
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```



Many variations possible

E.g.,

- 1. No reader kept waiting unless writer has permission to use shared object
- 2. Or, once writer is ready, it performs write asap
- These variations may suffer from starvation
- Problem can be solved through reader-writer locks

Dining-Philosophers Problem

- Philosophers spend their lives thinking and eating
- Don't interact with their neighbors
- Occasionally try to pick up 2 chopsticks (one at a time) to eat from bowl
 - ▷ Need both to eat, then release both when done
- In case of 5 philosophers, shared data
 Bowl of rice (data set)
 Semaphore chopstick [5] initialized to I

Dining-Philosophers Problem Algorithm

► The structure of Philosopher i:

```
do {
    wait ( chopstick[i] );
    wait ( chopStick[ (i + 1) % 5] );
    // eat
    signal ( chopstick[i] );
    signal ( chopstick[ (i + 1) % 5] );
    // think
} while (TRUE);
```

What is the problem with this algorithm?

Dining-Philosophers: Deadlock!

RICE

Each philosopher

Grabs their left chopstickWaits for their right chopstick

Deadlock!

Problems with Semaphores

Incorrect use of semaphore operations:

- ▷ signal(mutex) wait(mutex)
- ▷ wait(mutex) wait(mutex)
- ▷ Omitting of wait(mutex) or signal(mutex) (or both)
- Deadlock and starvation

Monitors

- Abstraction providing convenient/effective synchronization
- Abstract data type, internal variables only accessible by code within the procedure
- Only one thread may be active within the monitor at a time

```
monitor monitor-name
{
    // shared variable declarations
    procedure P1 (...) { .... }
    ...
    procedure Pn (...) { .....}
    Initialization code (...) { ... }
```


condition x, y;

Two operations on a condition variable:
 x.wait() suspends the thread until x.signal()
 x.signal() resumes a thread (if any) that invoked x.wait()
 If no x.wait() on variable, then it has no effect

Monitor with Condition Variables

Condition Variables Choices

If P invokes x.signal(), with Q in x.wait(), what happens next?
 If Q is resumed, then P must wait

Options include

- ▷ Signal & wait: P waits until Q leaves or waits for another condition
- Signal & continue: Q waits until P leaves the monitor or waits for another condition
- ▷ Both have pros and cons, language implementer can decide
- ▷ Implemented in many languages including Mesa, C#, Java

```
monitor DiningPhilosophers
{
 enum { THINKING; HUNGRY, EATING) state[5];
 condition self[5];
 void pickup (int i) {
     state[i] = HUNGRY;
     test(i);
     if (state[i] != EATING) self[i].wait();
 }
```

```
monitor DiningPhilosophers
ł
 enum { THINKING; HUNGRY, EATING) state[5];
 condition self[5];
                             Philosopher i is hungry
 void pickup (int i) {
     state[i] = HUNGRY;
     test(i);
     if (state[i] != EATING) self[i].wait();
 }
```

```
monitor DiningPhilosophers
{
  enum { THINKING; HUNGRY, EATING) state[5];
  condition self[5];
```

```
monitor DiningPhilosophers
ł
 enum { THINKING; HUNGRY, EATING) state[5];
 condition self[5];
 void pickup (int i) {
     state[i] = HUNGRY;
     test(i);
     if (state[i] != EATING) self[i].wait();
 }
```

If i can't eat, i goes to sleep

```
void putdown (int i) {
   state[i] = THINKING;
   // test left and right neighbors
   test((i + 4) % 5);
   test((i + 1) % 5);
}
```

Solution to Dining Philosophers


```
void test (int i) {
    if ( (state[(i + 4) % 5] != EATING) &&
    (state[i] == HUNGRY) &&
    (state[(i + 1) % 5] != EATING) ) {
         state[i] = EATING ;
         self[i].signal () ;
    }
}
initialization code() {
    for (int i = 0; i < 5; i++)
         state[i] = THINKING;
```

void test (int i) { if ((state[(i + 4) % 5] != EATING) && (state[i] == HUNGRY) && (state[(i + 1) % 5] != EATING)) { state[i] = EATING ; self[i].signal () ; If i's neighbors are not eating initialization code() { and i is hungry, i starts eating for (int i = 0; i < 5; i++) state[i] = THINKING;

Each philosopher i invokes the operations pickup() and putdown() in the following sequence:

DiningPhilosophers.pickup (i); EAT DiningPhilosophers.putdown (i);

No deadlock, but starvation is possible
 Why?
 Can you address it?


Need simple, efficient atomic ops

- Hardware primitives: test&set, swap, transactional memory
 Think about traffic while busy waiting
- Need higher level abstractions for programmability
 Semaphores, Monitors & Condition Variables
 - ▷ Support in the OS for waiting/sleeping and waking up
- A few classical problems
 - \triangleright Bounded buffer
 - ▷ Readers/writer
 - ▷ Dining philosophers